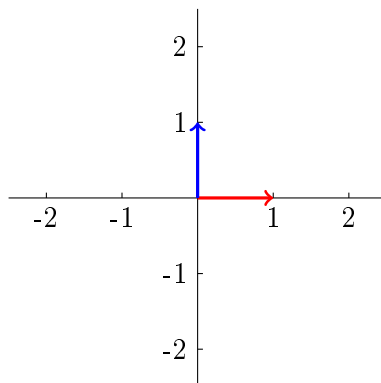


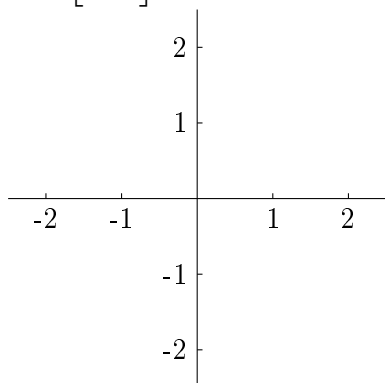
**MATH 21B, FEBRUARY 7: ROTATIONS, REFLECTIONS, DILATIONS,  
PROJECTIONS, AND SHEARS**

- (1) Consider the vectors  $\vec{e}_1$  and  $\vec{e}_2$  in  $\mathbb{R}^2$ .

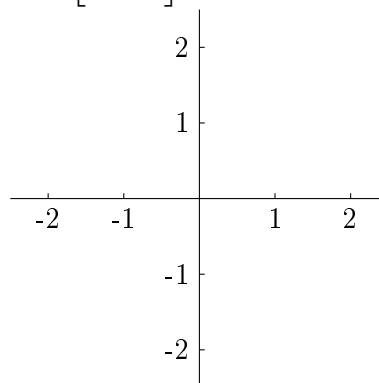


In each part below, you are given a matrix  $A$ . Draw what happens to the vectors  $\vec{e}_1$  and  $\vec{e}_2$  after applying the linear transformation  $T(\vec{x}) = A\vec{x}$ . Describe the effect of the linear transformation in words.

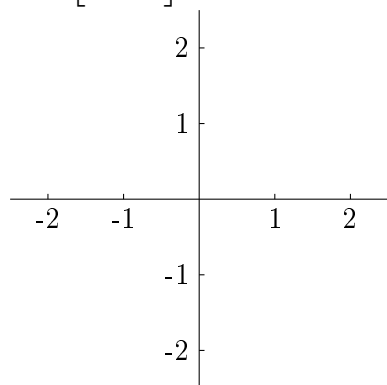
(a)  $A = \begin{bmatrix} 2 & 0 \\ 0 & 1 \end{bmatrix}$



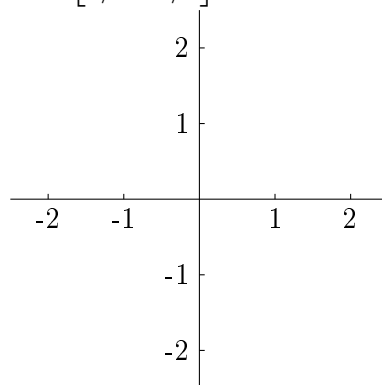
(b)  $A = \begin{bmatrix} 1 & -1 \\ 0 & 1 \end{bmatrix}$



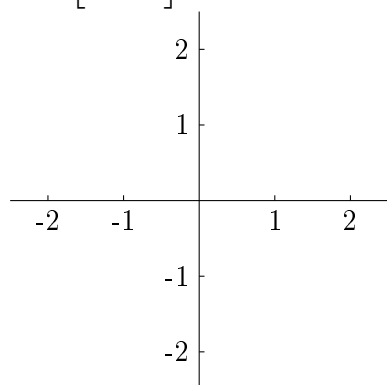
(c)  $A = \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix}$



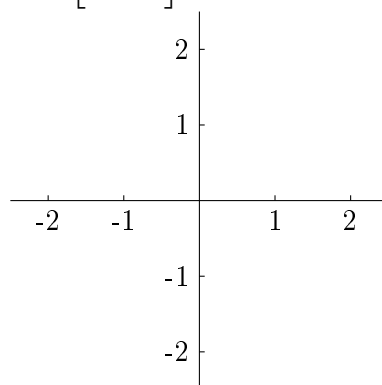
(e)  $A = \begin{bmatrix} 1/2 & 1/2 \\ 1/2 & 1/2 \end{bmatrix}$



(d)  $A = \begin{bmatrix} 1 & -1 \\ 1 & 1 \end{bmatrix}$



(f)  $A = \begin{bmatrix} 2 & 0 \\ 0 & -1 \end{bmatrix}$



(2) For each of the following linear transformations from  $\mathbb{R}^2$  to  $\mathbb{R}^2$ , write down its matrix.

(a) Rotation counterclockwise by an angle  $\theta$  around the origin. (Where does this transformation send the vectors  $\begin{bmatrix} 1 \\ 0 \end{bmatrix}$  and  $\begin{bmatrix} 0 \\ 1 \end{bmatrix}$ ?)

(b) Orthogonal projection onto the line  $y = 3x$ .

(c) Orthogonal projection onto the line  $y = 3x$ , followed by dilation by a factor of 2 (i.e. double the length of all vectors).

Given an  $n \times p$  matrix  $A$ , and a  $p \times m$  matrix  $B$ , we define the *matrix product*  $A \cdot B$  as follows. If  $B$  has column vectors

$$B = [\vec{v}_1 \quad \vec{v}_2 \quad \cdots \quad \vec{v}_m]$$

then  $A \cdot B$  (or just  $AB$ ) is the  $n \times m$  matrix

$$AB = [A\vec{v}_1 \quad A\vec{v}_2 \quad \cdots \quad A\vec{v}_m]$$

$A$  represents a linear transformation  $\mathbb{R}^p \rightarrow \mathbb{R}^n$ , and  $B$  represents a linear transformation  $\mathbb{R}^m \rightarrow \mathbb{R}^p$ ;  $A \cdot B$  represents the *composition*, which is a linear transformation  $\mathbb{R}^m \rightarrow \mathbb{R}^n$ .

(3) Let  $A = \begin{bmatrix} -2 & 3 \\ 1 & 2 \end{bmatrix}$  and  $B = \begin{bmatrix} 4 & 7 \\ 5 & 1 \end{bmatrix}$ . Find  $AB$  and  $BA$  (if they make sense).

(4) Let  $A = \begin{bmatrix} 1 & 4 \\ -3 & 1 \\ 0 & 0 \end{bmatrix}$  and  $B = \begin{bmatrix} 0 & 2 & 1 \end{bmatrix}$ . Find  $AB$  and  $BA$  (if they make sense).

(5) Let  $A = \begin{bmatrix} 1 & 2 \end{bmatrix}$  and  $B = \begin{bmatrix} 3 \\ 4 \end{bmatrix}$ . Find  $AB$  and  $BA$  (if they make sense).

(6) For any  $n$ , let  $I_n$  denote the matrix with 1's along the main diagonal and zeroes everywhere else: this is called the *identity matrix*. If  $A$  is an  $n \times m$  matrix, what is  $I_n A$ ? How about  $A I_m$ ?

(7) In 2(b), you found the matrix  $A$  for projection onto the line  $y = 3x$ . What is  $A^2$ ?